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**Cosmetic hands for
arm prostheses**

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Foreword

This translation has been made based on the original Japanese Industrial Standard revised by the Minister of International Trade and Industry and the Minister of Health and Welfare, through deliberations at the Japanese Industrial Standards Committee in accordance with the Industrial Standardization Law:

Date of Establishment: 1990-04-01

Date of Revision: 1995-10-01

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In the event of any doubts arising as to the contents,
the original JIS is to be the final authority.

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Cosmetic hands for arm prostheses

1 Scope This Japanese Industrial Standard specifies the cosmetic hands for arm prostheses (hereafter referred to as “hands”). However, the hands for infants and children shall be excluded.

Remarks 1 The normative reference of this Standard are shown below.

JIS B 0207 *Metric fine screw threads*

JIS T 9223 *Cosmetic gloves for artificial hands*

2 The units and numerical values given in { } in this Standard are based on the traditional unit system and are appended for information.

2 Definitions of terms The definitions of main terms used in this Standard shall be as follows.

The names of parts for hands are based on attached figures 1 to 3.

- (1) **cosmetic hands** functionally unmovable terminal equipment for arm prostheses taking the form of a human hand with five fingers, of which appearance is arranged by the cosmetic gloves for arm prostheses (hereafter referred to as “cosmetic gloves”)
- (2) **core** filler to be put in the cosmetic gloves in order to keep the position and form of hands and fingers, two kinds of which; skeletal and soft fillers
- (3) **skeletal core** filler to keep the hands and fingers in the specific position
- (4) **soft core** filler to keep the form of hands and fingers
- (5) **wrist rotation unit** unit to rotate the wrist of hands transitively

3 Types and symbols The types and symbols shall be as shown in table 1.